# The Care and Usage of Vectors

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# 1 Administrivia

## Announcements

### Assignment

Carefully read collision.c and Sections 4.1 and B.1–B.5. Note that collision.c is fairly "literate:" good identifier names, high-level overviews, details where necessary, use of whitespace, splitting lines to maximize readability. Use it as a model.

## From Last Time

Experimentation with polygon.c.

#### Outline

- 1. Finish-up polygon.c.
- 2. Vectors. Data structures and code.
- 3. Discussion of collision.c.

## Coming Up

Continued study of collision.c.

# 2 polygon.c

20 minutes to tie up loose ends. Turn in to kelliher[at]goucher.edu by beginning of next class.

# 3 Vectors

Operating systems is the application of data structures and algorithms. Computer graphics is the application of data structures, algorithms, trigonometry, linear algebra, Calculus, and differential equations.

- 1. Scalars.
- 2. Correspondence between points and vectors.
- 3. Forming a vector from two points.
- 4. Vector length: |u|.
- 5. Scaling vectors:  $\alpha u$ .
- 6. Adding vectors.
- 7. Forming a new point from a point and a vector.
- 8. Normalizing a vector:  $\hat{u} = \frac{1}{|u|}u$ .

Not the same as a normal vector.

9. Dot product properties:

(a) 
$$|u|^2 = u \cdot u$$
.

- (b)  $\cos \theta = \frac{u \cdot v}{|u||v|}$ , where  $\theta$  is the angle between u and v.
- (c) The projection of u onto v is  $|u| \cos \theta = \frac{u \cdot v}{|v|}$ Note that this is a scalar. What if I need a vector?

## **3.1** Data Structures and Code

This is all 2-D. It should be extended to 3-D.

1. Basic data structure:

```
typedef struct Vector2
{
    GLdouble x, y;
} Vector2;
```

2. Vector length:

```
double distanceSquared(double x, double y)
{
    return x * x + y * y;
}
double vectorLength(Vector2 v)
{
    return sqrt(distanceSquared(v.x, v.y));
}
```

Square root and division are expensive. Avoid where possible.

3. Scalar, vector product:

```
Vector2 scalarProduct(double s, Vector2 v)
{
    v.x *= s;
    v.y *= s;
    return v;
}
```

4. Dot product:

```
double dotProduct(Vector2 a, Vector2 b)
{
    return a.x * b.x + a.y * b.y;
}
```

5. Vector normalization:

```
Vector2 normalize(Vector2 v)
{
    double length = vectorLength(v);
    v.x /= length;
    v.y /= length;
    return v;
}
```

6. Vector sum:

```
Vector2 vectorSum(Vector2 a, Vector2 b)
{
    a.x += b.x;
    a.y += b.y;
    return a;
}
```

## 4 collision.c

- 1. main(): Note use of srand().
- 2. init(): Calls initBalls(), little else.
- 3. initBalls:
  - (a) First off, we need a better object manager. More precisely, we need an object manager.

(b) The "object" definitions:

```
typedef struct Color
{
    GLdouble r, g, b;
} Color;

typedef struct Ball
{
    Vector2 position; /* Ok, so it's not really a vector. Sue me. */
    Vector2 velocity;
    GLdouble radius;
    GLdouble mass;
    Color color;
    GLuint handle;
} Ball;
```

These should be proper classes.

- (c) Note setting of basic object attributes. These should be kept in a file and handled by the object manager.
- (d) Note compilation of object rendering primitives via individual display lists.

#### 4. placeBalls():

(a) Placement of the first ball along unit circle.

Velocity computation. Target: origin. Scaling velocity.

Translating position to circle of radius 40.

- (b) Avoiding initial collision: Constrained placement of second ball;  $\pi/4$  or more away.
- (c) Options: Aiming second ball at a point other than the origin. Computing and normalizing the velocity vector.

Making the second ball stationary, at an arbitrary position.