

CS250 Lab 14 – A Universal Turing Machine

Objectives: In this lab you will learn how to

- use a universal TM

A universal TM, U , is a TM that simulates other TMs. By providing a description of all transitions for some TM M and the initial contents of a input tape for M , U can simulate M . The file `ex14-universal` is a 3-tape machine which implements a universal TM. The first tape holds a description of M 's transitions. The second tape hold M 's internal tape. The third tape holds M 's internal state.

We first establish some conditions on M . M is a single tape machine with one initial state q_1 and one final state q_2 and we will assume that the blank symbol is symbol `a1` in M 's alphabet.

We now will describe a method to encode M 's tape symbols, states, and transitions as strings of 0's and 1's. Each state q_i in M is encoded as 1^i (for example q_4 is encoded as `1111`), and each tape symbol a_j is similarly encoded as 1^j . Finally, we encode the move symbols L, S, and R as `1,11`, and `111`, respectively. The symbol 0 suffixes each string of 1's. So if the internal tape of M is `a3 a5 a2` then this will be encoded as `1110111110110`.

The encoding of the transitions requires more explanations. Suppose one of M 's transitions is $(q_h, a_i) \rightarrow (q_j, a_k, d_l)$ where $d_1=L$, $d_2=S$, and $d_3=R$. This signifies that if M is in state q_h with the tape head on a_i , then M will overwrite a_i with a_k , move the head in the d_l direction, and move to state q_j . Each transition is encoded as $1^h 0 1^i 0 1^j 0 1^k 0 1^l 0$ with all encoded transitions concatenated together to form the machine description for `tape1`. For example, one would encode $(q_1, a_3) \rightarrow (q_2, a_5, S)$ as `101110110111110110` within `tape1`.

How does `ex12-universal` work? In brief, U executes a continuous loop. First, U performs a linear search in `tape1` for a transition that matches the state in `tape3` and a symbol at the current head position on `tape2`. If the current state and symbol do not match the transition, U , proceeds to the next encoded transition in `tape1`. If the state and symbol match, U changes `tape3` to hold the new state and `tape2` to overwrite the current symbol with the transition's new symbol, and moves `tape2` head in the direction indicated by the transition's direction symbol. Then `tape3` is checked to see if it is the halting state (q_2) in which case U accepts; otherwise U starts the loop again.

The lengthy encoding makes interesting TMs tedious to encode and input. However, a very simple machine is manageable. The machine `ex14.2` is a transducer (it modifies the tape rather than accepting a language) which converts every `a` to `b` and accepts when it reaches the end of the string. Open up this TM and test it.

We can encode the tape alphabet as `blank→1, a→11, b→111`.

We can encode the transition $(q_1, a) \rightarrow (q_1, b, R)$ as `101101011101110`.

We can encode the second transition as `101011010110`.

Therefore the machine description is `101101011101110101011010110` for `tape1`.

Suppose we want our initial input to be **aaa**. This we encode as 110110110 for tape2. Finally, as always tape3 must hold 1 to signify our initial state q1.

Assignment 1:

Perform a Fast Run of the universal machine with the input described above. It should accept. Explain the values on tapes 2 and 3 after the universal machine accepts.

The existence of a universal Turing machine means that TMs can now be considered equivalent to general purpose digital computers which can be programmed to do different jobs at different times!

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