

SPIM S20: Syscalls

James R. Larus
 Edited by Tom Kelliher

Copyright ©1990–2004 by James R. Larus
 (This document may be copied without royalties,
 so long as this copyright notice remains on it.)

SPIM provides a small set of operating-system-like services through the system call (`syscall`) instruction. To request a service, a program loads the system call code into register `$v0` and the arguments into registers `$a0..$a3` (or `$f12` for floating point values). System calls that return values put their result in register `$v0` (or `$f0` for floating point results). For example, to print “the answer = 5”, use the commands:

```
.data
str: .asciiz "the answer = "
.text
li $v0, 4      # system call code for print_str
la $a0, str    # address of string to print
syscall       # print the string

li $v0, 1      # system call code for print_int
li $a0, 5      # integer to print
syscall       # print it
```

Service	System Call Code	Arguments	Result
print_int	1	<code>\$a0</code> = integer	
print_float	2	<code>\$f12</code> = float	
print_double	3	<code>\$f12</code> = double	
print_string	4	<code>\$a0</code> = string	
read_int	5		integer (in <code>\$v0</code>)
read_float	6		float (in <code>\$f0</code>)
read_double	7		double (in <code>\$f0</code>)
read_string	8	<code>\$a0</code> = buffer, <code>\$a1</code> = length	
sbrk	9	<code>\$a0</code> = amount	address (in <code>\$v0</code>)
exit	10		
print_character	11	<code>\$a0</code> = character	
read_character	12		character (in <code>\$v0</code>)
open	13	<code>\$a0</code> = filename, <code>\$a1</code> = flags, <code>\$a2</code> = mode	file descriptor (in <code>\$v0</code>)
read	14	<code>\$a0</code> = file descriptor, <code>\$a1</code> = buffer, <code>\$a2</code> = count	bytes read (in <code>\$v0</code>)
write	15	<code>\$a0</code> = file descriptor, <code>\$a1</code> = buffer, <code>\$a2</code> = count	bytes written (in <code>\$v0</code>)
close	16	<code>\$a0</code> = file descriptor	0 (in <code>\$v0</code>)
exit2	17	<code>\$a0</code> = value	