

## CS250 Lab 14 – A Universal Turing Machine

**Objectives:** In this lab you will learn how to

- use a universal TM

A universal TM,  $U$ , is a TM that simulates other TMs. By providing a description of all transitions for some TM  $M$  and the initial contents of a input tape for  $M$ ,  $U$  can simulate  $M$ . The file `ex14-universal` is a 3-tape machine which implements a universal TM. The first tape holds a description of  $M$ 's transitions. The second tape hold  $M$ 's internal tape. The third tape holds  $M$ 's internal state.

We first establish some conditions on  $M$ .  $M$  is a single tape machine with one initial state  $q_1$  and one final state  $q_2$  and we will assume that the blank symbol is symbol `a1` in  $M$ 's alphabet.

We now will describe a method to encode  $M$ 's tape symbols, states, and transitions as strings of 0's and 1's. Each state  $q_i$  in  $M$  is encoded as  $1^i$  (for example  $q_4$  is encoded as `1111`), and each tape symbol  $a_j$  is similarly encoded as  $1^j$ . Finally, we encode the move symbols L, S, and R as `1,11`, and `111`, respectively. The symbol 0 suffixes each string of 1's. So if the internal tape of  $M$  is `a3 a5 a2` then this will be encoded as `1110111110110`.

The encoding of the transitions requires more explanations. Suppose one of  $M$ 's transitions is  $(q_h, a_i) \rightarrow (q_j, a_k, d_l)$  where  $d_1=L$ ,  $d_2=S$ , and  $d_3=R$ . This signifies that if  $M$  is in state  $q_h$  with the tape head on  $a_i$ , then  $M$  will overwrite  $a_i$  with  $a_k$ , move the head in the  $d_l$  direction, and move to state  $q_j$ . Each transition is encoded as  $1^h 0 1^i 0 1^j 0 1^k 0 1^l 0$  with all encoded transitions concatenated together to form the machine description for `tape1`. For example, one would encode  $(q_1, a_3) \rightarrow (q_2, a_5, S)$  as `101110110111110110` within `tape1`.

How does `ex12-universal` work? In brief,  $U$  executes a continuous loop. First,  $U$  performs a linear search in `tape1` for a transition that matches the state in `tape3` and a symbol at the current head position on `tape2`. If the current state and symbol do not match the transition,  $U$ , proceeds to the next encoded transition in `tape1`. If the state and symbol match,  $U$  changes `tape3` to hold the new state and `tape2` to overwrite the current symbol with the transition's new symbol, and moves `tape2` head in the direction indicated by the transition's direction symbol. Then `tape3` is checked to see if it is the halting state ( $q_2$ ) in which case  $U$  accepts; otherwise  $U$  starts the loop again.

The lengthy encoding makes interesting TMs tedious to encode and input. However, a very simple machine is manageable. The machine `ex14.2` is a transducer (it modifies the tape rather than accepting a language) which converts every `a` to `b` and accepts when it reaches the end of the string. Open up this TM and test it.

We can encode the tape alphabet as `blank→1`, `a→11`, `b→111`.

We can encode the transition  $(q_1, a) \rightarrow (q_1, b, R)$  as `101101011101110`.

We can encode the second transition as `101011010110`.

Therefore the machine description is `101101011101110101011010110` for `tape1`.

Suppose we want our initial input to be **aaa**. This we encode as 110110110 for tape2. Finally, as always tape3 must hold 1 to signify our initial state q1.

**Assignment 1:**

Perform a Fast Run of the universal machine with the input described above. It should accept. Explain the values on tapes 2 and 3 after the universal machine accepts.

The existence of a universal Turing machine means that TMs can now be considered equivalent to general purpose digital computers which can be programmed to do different jobs at different times!

Submit your files in goucherLearn for grading.